



FINAL-YEAR Project

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HEADTAIL simulation studies of Landau damping through octupoles in the LHC

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I. Introduction

This internship was performed at the European Organization for Nuclear Research (CERN) and more precisely in the Impedance and Collective Effects section (ICE), a section of the Accelerator Beam Physics group (ABP) which itself is part of the Beam department (BE).

During this internship my work was in particle accelerator physics and especially in the beam instabilities field. Therefore, in the first part of this report I will present some accelerator physics and beam instability basics. Then I will present one of the simulation codes that I was using and finally I will show the results of my work.

As the beam intensity increases, the beam can no longer be considered as a collection of non-interacting particles. This introduces the notion of collective effects. There are four different types of collective effects. The first one is the space charge which is the interaction of the charged particles with themselves. On the other hand, the interaction of the particles and their environment introduces the wake fields and the impedance concept. The third and the fourth types are induced by the interaction of the charged particles with other charged particles, which leads to electron cloud effects and beam-beam effects. These perturbations can lead to coherent and incoherent effects as well as beam losses. and heating That's why they should be well studied and controlled. This internship was mainly about the impedance effects on the beam and tried to compare theory and simulations in a special case to verify the reliability of the simulation code in this case.

II. Useful concepts for the understanding of this report

Section II begins with some accelerator physics definitions followed by some details about impedance effects and stability diagrams.

II.1. Some accelerator physics basics

In a particle accelerator, charged particles follow the main designed orbit doing oscillations around it in both transverse directions (x) and (y). These transverse oscillations are called betatron oscillations. Their number per turn is called the tune (Qx,Qy). On the other hand, the particles make oscillations in the longitudinal plane as well. They are called synchrotron oscillations and their number per turn is called synchrotron tune (Qs) [1].

Since all the particles of the beam have not a unique momentum (p), there is a momentum spread (Δ p). Therefore the particles do not all follow the same trajectory. This results in a tune spread (Δ Q). One can now define the chromaticity Q' as following:

$$Q' = \frac{\Delta Q}{\Delta p / p} \tag{1}$$

Another important concept is the emittance of a beam (ϵ). The emittance in one of the directions is the area of the beam in the longitudinal phase space and the area divided by π in the transverse ones.

For a given configuration of an accelerator, there is an energy called transition energy. Below this energy the revolution frequency increases with the energy and above it the revolution frequency decreases when the energy increases. It is described by the slip factor η (transition energy when η =0) [2].

$$\eta = \frac{\frac{d\omega}{\omega}}{\frac{dp}{p}}$$
 (2)

II.2. Impedances and wake fields

If the beam is in a perfectly conducting and smooth beam pipe, a ring of charged particles of opposite sign will be formed on its wall and will travel with the beam; it is called induced current. This induced current is formed where the electric field ends and leads to a real tune-shift. If the beam pipe is not perfectly conducting or has discontinuities, the induced current will be slowed down creating electromagnetic fields called wake fields. These fields create a complex tune-shift which leads to instability.

These wake functions are real functions of time. Their Fourier transform gives the impedance which is then a function of frequency. The concept of impedance has been introduced by Sessler and Vaccaro [3] because the calculations are easier in the frequency domain and especially for cases where the relativistic factor $\beta \neq 1$ (in which a part of the wake field is in front of the beam). The relations linking the wake functions and impedances are given by [4,5]:

$$Z_{-\infty}^{\prime\prime}(\omega) = \int_{-\infty}^{+\infty} W'(z) e^{jkz} \frac{dz}{v} = \int_{-\infty}^{+\infty} W'(t) e^{jks} e^{-j\omega t} dt,$$

$$Z^{\perp}(\omega) = -j \int_{-\infty}^{+\infty} W(z) e^{jkz} \frac{dz}{v} = -j \int_{-\infty}^{+\infty} W(t) e^{jks} e^{-j\omega t} dt.$$

$$W'(z) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} Z^{\prime\prime}(\omega) e^{-jkz} d\omega = \frac{1}{2\pi} \int_{-\infty}^{+\infty} Z^{\prime\prime}(\omega) e^{-jks} e^{j\omega t} d\omega,$$

$$W_{-}(z) = \frac{j}{2\pi} \int_{-\infty}^{+\infty} Z^{\perp}(\omega) e^{-jkz} d\omega = \frac{j}{2\pi} \int_{-\infty}^{+\infty} Z^{\perp}(\omega) e^{-jks} e^{j\omega t} d\omega.$$
(3)

Where:

W(z) is the transverse wake function, W'(z) the longitudinal one, $Z^{\perp}(\omega)$ and $Z''(\omega)$ are the transverse and longitudinal impedances, all functions of the azimuthal mode (m) (see section II.3), s is the longitudinal coordinate, j the imaginary unit, k the wavenumber, v the velocity and z=s-v.t.

II.3. Instabilities and Landau damping

Wake fields have two effects on the beam:

- A long-range effect which means that the wake field of a particle in a bunch affects other bunches or even the same bunch after one or more turns.
- A short-range effect, when the effect on the other bunches is negligible, where just the interaction between the particles of a bunch and the internal circulation can induce internal coherent modes and beam instability [5,6].

The betatron frequency of a particle depends on its instantaneous momentum; therefore there is a betatron frequency shift between the head and the tail of a bunch. This is the physical reason of the so called head-tail instability. This instability is described by a mode number (m), also called the head-tail mode number, which represents the number of betatron wavelengths per synchrotron period, which is also the number of nodes of the signal given by a pick up of the average transverse displacement along a bunch (*Figure 1*).



Figure 1: Transverse signal at a pick-up for four different modes

Sacherer unified the long-range and the short-range effects by introducing a new mode number (q), called the radial mode number [6,7]. Therefore, to a given radial mode and to a given head-tail mode number corresponds a tune-shift $\Delta \omega_{c, mq}^{x}$. At sufficiently low intensity the most coherent mode (see the following paragraph for the definition of coherent), which is the one with the largest value of the coherent tune-shift, is given by the Sacherer formula for q=m:

$$\Delta \omega_{c,mm}^{x} = \left(\omega_{c} - \omega_{x0} - m\omega_{s}\right) = \left(|m|+1\right)^{-1} \frac{je\beta I_{b}}{2m_{0}\gamma Q_{x0}\Omega_{0}L_{b}} \frac{\sum_{k=-\infty}^{k=+\infty} Z_{x}\left(\omega_{k}^{x}\right)h_{m,m}\left(\omega_{k}^{x}-\omega_{\xi_{x}}\right)}{\sum_{k=-\infty}^{k=+\infty}h_{m,m}\left(\omega_{k}^{x}-\omega_{\xi_{x}}\right)}$$
(4)
with
$$h_{m,m}\left(\omega\right) = \frac{\tau_{b}^{2}}{2\pi^{4}}\left(|m|+1\right)^{2} \frac{1+\left(-1\right)^{|m|}\cos\left(\omega\tau_{b}\right)}{\left[\left(\omega\tau_{b}/\pi\right)^{2}-\left(|m|+1\right)^{2}\right]^{2}}$$

with

 $\omega_k^x = (k + Q_{x0}) \Omega_0 + m\omega_s, \qquad -\infty \le k \le +\infty$

Where $(\Delta \omega_{c, mm}^{x})$ is the coherent complex frequency-shift for the mode (mm) in the horizontal plane (x), (ω_{s}) is the synchrotron frequency, (I_b) is the bunch current, (mo) is the particle mass,

 (Ω_0) is the revolution frequency, (L_b) is the full bunch length in m, (Z_x) is the horizontal component of the impedance, (τ_b) is the total bunch length in s and finally with $\omega_{\xi_x} = Q_{x0} \Omega_0 \frac{\xi_x}{\eta}$ where $\xi_x = Q'/Q$ and (η) the slip factor.

As a convention and since I am only using q=m, I will only talk about the mode m instead of mm.

As the bunch intensity increases, the different head-tail modes can no longer be treated separately, and the wake fields couple the modes together. This mode coupling has a threshold that depends on many factors like the transition energy, the chromaticity, longitudinal emittance, etc. Some of the parameters can be adapted to make the beam the most stable possible, but there are always other limitations and one is always forced to make trade-off between different criteria.

One of the mechanisms that stabilizes the coherent instabilities is the Landau damping. Besides its mathematical formalism, it can be described physically as the transfer of energy from the coherent mode into incoherent motion. Every particle has its own incoherent motion and there may also be a coherent motion of the beam or a group of particles of the beam. These two different motions have different frequencies. A transfer of energy from the coherent instability to the incoherent motion is possible if the incoherent frequencies include the coherent mode frequency. That's why a tune spread is needed to stabilize a beam and this tune spread is obtained by introducing non-linearities. Indeed the larger the tune spread between the difference particles, the larger the incoherent frequencies interval is and the more likely it is to contain the coherent mode frequency. If the coherent frequency is outside the incoherent spectrum then there is no Landau damping and any perturbation would lead to instability. The Landau damping from octupoles for coherent instabilities is discussed from the following dispersion relation[5,6,8,9]:

$$1 = -\Delta Q_{coh}^{x} \int_{J_{x}=0}^{+\infty} dJ_{x} \int_{J_{y}=0}^{+\infty} dJ_{y} \frac{J_{x}}{Q_{c} - Q_{x} \left(J_{x}, J_{y}\right)}}{Q_{c} - Q_{x} \left(J_{x}, J_{y}\right) - m Q_{s}},$$
(5)

With:

$$Q_x(J_x, J_y) = Q_0 + a_0 J_x + b_0 J_y$$
.

Where (Q_c) is the coherent betatron tune, (J_x) and (J_y) are the action variables in the horizontal and the vertical planes, (f) the distribution function, (ΔQ_{coh}^{x}) is the horizontal coherent tune-shift, (Q_x(J_x,J_y)) is the horizontal tune in presence of octupoles, (Q_s) is the synchrotron tune, (m) the head-tail mode; and (a₀) and (b₀) two constants which depend on the octupoles strength and number.

The stability condition is a real Q_c. One can then scan the real parameter Q_c-Q₀-mQ_s (stability limit) from $-\infty$ to $+\infty$ and observes the locus of the tune-shift obtained from the dispersion relation traced out in a diagram where the horizontal axis is the real part of the tune-shift and the vertical one is the opposite of its imaginary part. This curve represents the stability boundary diagram. If the coherent tune-shift is inside the curve, then the beam is stable and if it is outside then the beam is unstable because Q_c would have a non-zero imaginary part (*Figure 2*) [6,7].



Figure 2: Example of a stability diagram

It is important to remember that Landau damping and maximizing the dynamic aperture are partly conflicting because Landau damping needs a spread of betatron frequencies which requires non-linearities. On the other hand, maximizing the dynamic aperture requires minimizing the non-linearities at large amplitudes. That's why a trade-off between Landau damping and dynamic aperture is necessary.

III. HEADTAIL simulation code

The HEADTAIL code is a tracking simulation tool that treats collective effects phenomena [10]. There are two versions of this code, HEADTAIL_ecloud and HEADTAIL_impedance which treat respectively the electron cloud interaction and the impedance one. In my study I was more interested in the impedance version of HEADTAIL because all of my work was about impedance effects. The other version has the same working physical principle. The code divides the bunch into many slices, then computes the interaction of each slice with the impedance defined at a precise point (kick point S). It can work with several bunches (multibunch version), several kicks (multi-kick version) and can keep in memory the wake field for several turns (multi-turn version). All these parameters can be set in the input file where the beam and the simulation parameters are also set. Then after these computes again the interaction. These steps are made for a number of turns which is set in the input file.



Figure 3: Working principle of the HEADTAIL_impedance code.

An example of the input file is given in *Appendix*, where one can find several beam parameters like the energy, the tune and the chromaticity. There are also optics parameters like the beta function, sextupoles strength and octupoles current (the current powering the octupoles and which is directly linked to its magnetic field strength), as well as simulation parameters like the number of turns, number of slices and memory of the wake.

The output of HEADTAIL has many files; the one which is interesting for this study is the one with the "_prt.dat" extension. This file has 22 columns. The most important of them for this study is the first one which is the time and the second one which is the average horizontal position. The other columns contain the other average positions, the emittances, momentum, etc.

This "_prt.dat" file is one of the complications I met in this work because it is huge (≈100Mb) which limited the number of simultaneous simulations because of the account storage capacity I was using.

Other important outputs are the "_trk.dat" and the "_hdtl.dat"; the first one contains the wake function used by HEADTAIL and the second one contains the average postion of the slices along the bunch which allows the user to see the coherent motion of the bunch.

IV. LHC simulations

After defining the parameters needed in the third section, I can now define exactly the objective of my work. The main idea is to benchmark HEADTAIL against theory from a stability point of view. There are four different outputs which will be considered in this study; the tuneshift that can be obtained from simulation and from theory, and the stabilizing octuple current also from both of them. The benchmark between HEADTAIL, theory and experiment has already been done on several aspects of beam instability. However, reproducing the stability diagram using HEADTAIL has never been done, and that's what makes the motivation of this work. So the main objective of this work is for a given stability diagram (current and transverse distribution defined), finding several points on the stability curve using theory, then HEADTAIL simulations are made to try to reproduce the curve using HEADTAIL.

First of all, I simulated the case of the LHC at 3.5 TeV, single bunch, linear bucket, 115 10⁹ particle per bunch, horizontal chromaticity 6 and only the dipolar component of the LHC impedance. The input file of this simulation is in *Appendix* for more details about the parameters of this simulation. The objective of this work is to reproduce the stability diagram, so the best attitude to have is to try to be as simple as possible to separate complications. That's why this first simulation and also all the following ones were made only to study the horizontal plane (chromaticity in the vertical one is 0 as well as the impedance) and considering only the dipolar component of the impedance.

Using Sacherer's formula (4) I computed the tune-shift for this case, which gave $\Delta Q = -1.64 \ 10^{-4} - j \ 3.78 \ 10^{-6}$. This value is compared to the one given by HEADTAIL. In the HEADTAIL output files one cannot get the tune-shift directly, so a step of post-processing of the outputs is necessary. To get the real tune-shift, a fast Fourier transform was made on the horizontal average position of the beam. Then to get the imaginary part of the tune-shift, an exponential fit of the average horizontal position is required to get the rise time (τ) which is directly linked to the imaginary part of the tune-shift through the following relation:

$$Im(\Delta Q) = -\frac{1}{\Omega_0 \tau} \tag{6}$$

with Ω_0 : the revolution angular frequency



Figure 4: Exponential fit of the average horizontal position of the beam

The average horizontal position is plotted in *Figure 4* as well as the average displacement of the slices of the bunch over 20 turns (small figure). It can be easily seen that the absolute value of the instability mode is 1 and after an exponential fit, the rise-time is 4.02s which gives an imaginary part of $-3.52 \, 10^{-6}$.

After doing a fast Fourier transform (FFT) over this average horizontal position, I obtained the values of *Figure 5*.



Figure 5: FFT of the average position (horizontal axis Δ Q/Qs, vertical one the FFT amplitude)

In Figure 5 the horizontal axis is Δ Q/Qs and on the vertical one the amplitude of the FFT. One can clearly see that the unstable mode is m=-1 mode and its real tune-shift is $-9.28 \ 10^{-5}$.

Sacherer's formula gives $\Delta Q = -1.64 \ 10^{-4} - j \ 3.78 \ 10^{-6}$ and the HEADTAIL simulation gives $\Delta Q = -9.28 \ 10^{-5} - j \ 3.52 \ 10^{-6}$. There is only 7% error on the imaginary part while there is almost a factor 1.8 on the real part. This result is very satisfactory since one finds the tune-shift within less than a factor 2 using a quite simple and approximated formula. One can notice this by comparing the computation time of each one. For Sacherer, it was less than 20 minutes, while a HEADTAIL simulation of 200 000 turns (less than 18s in the LHC) takes more or less 5 days (without any post-processing).

The tune-shift value was the first comparison between HEADTAIL and theory (Sacherer). Now the second approach is to put both of the tune-shifts on a diagram where the horizontal axis is the real tune-shift and the vertical one is the opposite of its imaginary part, we obtain two points. Then using the dispersion equation (5), the stability diagram can be plotted for different transverse distributions and octupoles currents. The idea then is to take a distribution, then to change the octupoles current until finding the current for which the point is exactly on the curve (stability limit). When the octupoles current increases, the area under the curve increases, meaning that the stability area increases. For each current there are two different curves; one of them is for the positive current and the other is for the negative one, because the stability limit for the same absolute value of a current, is different. The stability diagram also depends on the transverse distribution of the bunch; here I compare a Gaussian one to a quasi-parabolic one [8]. One can already expect that the Gaussian should be more stable so needs less current because it assumes an infinite distribution where the tails can absorb a part of the energy. While the quasi-parabolic one underestimates the stability (needs more current) because the LHC collimators are set at 6σ (the quasi-parabolic extends to 3.2σ).

Doing this scan of octupoles current for a given distribution, one can get the theoretical stabilizing current (the one given by the stability diagram), then it is to be compared to the simulated one which is given by HEADTAIL. The one given by HEADTAIL is obtained by simulating several cases with different octupoles current and plotting the average horizontal position. When the position is stable, it means that the stabilizing current is less than the one used. When it is unstable, it means that it needs more current (in absolute value). This scan of octupoles current gives then a range of the simulated stabilizing current which can be compared to the one from the stability diagram.



Figure 6: Stability diagram for the LHC for 2 different distributions and both of the current signs.

In *Figure 6* I did a scan of the octupoles current and I found for the LHC tune-shift given by the HEADTAIL simulations, a stabilizing current of -16A (red curve) and +26.5A (blue curve) for a Gaussian distribution. While for the quasi-parabolic one, it was higher as I expected, -37A and +31A. In all the following cases I will just use the Gaussian distribution since HEAD-TAIL uses a Gaussian distribution too.

Then I launched an intensity scan using HEADTAIL and I obtained the following results.



Figure 7: Average horizontal position for different octupoles currents: 0A (red), -5A (green) and -10A (blue).



Figure 7: Average horizontal position for different octupoles currents: -10A (red), -15A (green) and -30A (blue).



Figure 8: Average horizontal position for different octupoles currents: 0A (red), 5A (green), 10A (blue) and 15A (magenta)



Figure 9: Average horizontal position for different octupoles currents: 15A (red), 20A (green) and 50A (blue).

The HEADTAIL current scan gave a negative stabilizing current between -5A and -10A, and a positive one between +10A and +15A. First of all, this result is confirming the fact that there is a shift between the positive and the negative current and it confirms that for this given tune-shift it is more efficient to stabilize with a negative current. There is a factor 2 between the two approaches. It could be an error in the implementation of the code, in the physics or a real difference between the stability diagram and HEADTAIL.

A first hypothesis was that the instability appears later in time, then we could not notice it in the previous simulations. For example when I first did the simulations I tried many different configurations. One of them was the linear and the non linear bucket for which I noticed that with a non-linear bucket the instability appears much later (*Figure 10.1*). So as a first test I tried to simulate the same case but over 500 000 turns instead of 200 000 (*Figure 10.2*).



Figure 10.1: Average horizontal position for 3 different settings. 200 000 turns linear bucket at 15A (blue), 200 000 turns non-linear bucket at 0A (green) and 500 000 turns non-linear bucket with 0A (red)



Figure 10.2: Average horizontal position for a 500 000 turns linear bucket with +15A

We notice on *Figure 10.2* that it is not a late appearance of the instability. The beam is still stable after 500 000 turns, the difference comes then from another reason.

V. Scan of the stability diagram

To avoid wasting time, especially since the simulations take a very long time, I continued the project keeping in mind that there is a factor 2 to try to justify later.

At this stage of the internship, I did several simulations and a comparison with theory, but the main goal to reach was to scan the stability diagram.

To be able to scan the stability diagram I had to change the impedance so that I could find other tune-shifts which are exactly on the same stability curve.

A first trial was to simulate the LHC again but without collimators and then try to change the beam intensity and try to find another point on the curve. But this wasn't successful because I couldn't reach the stability curve using this model.

The second idea of impedance was the resonator impedance. In this model the transverse impedance is written as following [4]:

$$Z_{m}^{\perp}(\omega) = \frac{\omega_{r}}{\omega} \frac{R_{\perp}}{1 + j Q\left(\frac{\omega}{\omega_{r}} - \frac{\omega_{r}}{\omega}\right)}$$
(7)

Where, (ω_r) is the resonance angular frequency, (Q) the quality factor and (R_{\perp}) is the shunt impedance.

Figure 11: Example of a resonator with $R_{\perp}=17.5M\Omega/m$, Q=1 and f=0.64 GHz. Thereal part of the impedance (blue curve), imaginary part of impedance (red curve), h_{11} (black curve)

By changing the three parameters, I tried to scan the stability diagram at -24.8A which also passes by the Sacherer tune-shift for LHC mode simulated in the previous section. After the scan I obtained the following *Figure 12*:

Figure 12: Scan of the stability diagram at -24.8A

In *Figure 12* the blue curve is plotted to show the shift between the positive and negative octupoles current, even though it is useless in this plot. The tune-shifts obtained for these impedances are given by Sacherer's formula; that's why when I chose a current I just took -24.8A (passing by Sacherer's tune-shift of the LHC) and not -16A (passing by the HEADTAIL tune-shift of the LHC).

After HEADTAIL simulations, I found a very strange result (*Figure 13*). The result was so strange that I had to check the reliability of every step of the analysis.

The first verification I did was to check if the slicing of the bunch was small enough to reproduce the wake field as it should be, because if the slices are too big the wake field will be deformed. The transverse wake function (G) is given by the following relation [4]:

$$G_{m}^{\perp}(t) = \frac{\omega_{r}^{2} R_{\perp}}{Q \overline{\omega}_{r}} e^{-\alpha t} \sin\left(\overline{\omega}_{r} t\right) \qquad \text{with:} \qquad \overline{\omega}_{r} = \omega_{r} \sqrt{1 - \frac{1}{4Q^{2}}} \qquad (8)$$
$$\alpha = \frac{\omega_{r}}{2Q}$$

Figure 13: Simulated scan of the stability diagram at -24.8A

Comparing the wake field given by Eq. (8) and the wake field used and fitted by HEADTAIL (output file with the extension "_trk.dat") I obtained the results *Figure 14*.

The wake fields are exactly the same, so the problem is not a problem of slicing. Then I tried to check the accuracy of the tune-shifts calculated from HEADTAIL. First of all, I tried to use SUSSIX which is a computer code for frequency analysis [11]. The result of SUSSIX was almost the same as the FFT. Then I checked the imaginary part of the tune shift. The first time I was fitting the horizontal position, I was using a code which fits the logarithm value of the module of the horizontal position. This time I used another code that fits directly the curve with an exponential; the result was the same (3% difference in the worst case) which means that the problem is not a problem of the HEADTAIL post-processing. Then I tried to check the accuracy of the code that compute Sacherer's formula. In this code the condition to stop summing terms is that the ratio of the first abandoned term and the sum is less than 10^{-12} . Then I put this condition to 10^{-10} which gave me exactly the same result. So we could think that there is no sum error in the Sacherer formula, but further investigations are needed.

At this stage I found an error in my implementation of the Sacherer formula. After I corrected this error, the Sacherer tune-shift changed. It has now a better real tune-shift compared to the HEADTAIL one but the imaginary part is still completely different from the HEADTAIL one. This means that now the points that were supposed to be on the stability edge changed their value and are not on the stability edge anymore. However, it is still important to solve the problem of the huge difference between HEADTAIL and Sacherer even if the points are not on the curve because anyway I will have to use Sacherer's formula to scan the curve again.

To check which of the values is wrong, I used the MOSES code (MOde coupling Single bunch instability in an Electron Storage ring) which is a code that computes the tune-shift and the transverse mode coupling threshold from a resonator impedance [12]. The advantage of this code is that it is very quick and very easy. For the five points I compared MOSES, Sacherer and HEADTAIL (without octupoles) and I obtained the following results:

Figure 15: Comparing HEADTAIL, MOSES and Sacherer for the first scan point (without octupoles)

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Figure 16: Comparing HEADTAIL, MOSES and Sacherer for the four other scan points

It can be easily noticed that HEADTAIL and MOSES are in good agreement while Sacherer's formula always gives a very different imaginary part.

The error is then most probably coming from the Sacherer formula. The first thing to check is the implementation. Dr. Elias Metral checked the values with his own implementation and he found results with more or less 40% error compared to the HEADTAIL value. Which is expected because Sacherer's formula is an approximated formula that should be valid within a factor 2. Since I already checked many times the implementation I am using and I didn't find any error, I wrote another one using a trapeze integral instead of a sum. This time I found much better results (in the worst case 66% error compared to HEADTAIL value, see Figure 17). So we could think now that there is indeed a numerical problem with the first method since I am using exactly the same parameters but just a different way to sum; investigations are ongoing.

	Rs (Mohm/m)	7,1	17,5	17,5	17,5	22,5
	Q	0,5	1	1	2	1
	f(GHz)	0,75	0,64	0,6	0,6	0,1
Headtail	Re(ΔQ)	1,42E-05	5,28E-05	4,49E-05	4,11E-05	7,63E-06
	Im(ΔQ)	-1,12E-05	-3,16E-05	-3,06E-05	-1,93E-05	-2,95E-06
MOSES	Re(ΔQ)	1,05E-05	3,23E-05	3,17E-05	2,25E-05	3,80E-06
	Im(ΔQ)	-1,14E-05	-3,13E-05	-3,10E-05	-1,97E-05	-3,89E-06
	error Re(ΔQ)	26%	39%	29%	45%	50%
	error Im(ΔQ)	2%	1%	1%	2%	32%
Sacherer	Re(ΔQ)	4,85E-06	3,09E-05	3,27E-05	2,57E-05	4,74E-06
	Im(ΔQ)	-1,72E-05	-3,43E-05	-3,39E-05	-2,32E-05	-3,67E-06
	error Re(ΔQ)	66%	41%	27%	38%	38%
	error Im(ΔQ)	55%	8%	11%	20%	24%

Figure 17: Comparison of HEADTAIL, MOSES and Sacherer (new implementation) and the error to the HEADTAIL value

With these results, the new Sacherer implementation is reliable. Now I can scan the stability diagram using this formula and then launch the HEADTAIL simulations with the found points. The scan of a curve can take a very long time; that's why this time I scanned the negative curve at -30A. With a higher current, the curve is bigger and it is easier to find points on it.

Figure 18: Scan of the stability diagram at -30A

The HEADTAIL simulations of these points gave again very disappointing results with more than a factor 3 between Sacherer and HEADTAIL, except for the last point (R=22.5M Ω /m,

Q=1 f =0.1GHz). When I checked with MOSES these five points I found results very close to HEADTAIL. The important thing I noticed was that the mode coupling threshold was much higher for the last point than all the others. That's most probably why it is the only point for which I got an agreement between HEADTAIL and Sacherer, because Sacherer's formula supposes that there is no mode-coupling and that every mode can be treated seperatly.

Figure 19: Mode coupling threshold for the 5 points, the simulated beam current is 0.207 mA (in dotted red curve). WASEF Raymond

Figure 19 shows the mode coupling threshold for the different points (in the simulation case the beam intensity is 0.207 mA), the horizontal axis is the beam intensity and the vertical one is the real tune-shift. It is clear that in the case of the last point the threshold is much higher than the other cases (mode coupling is when 2 different tune-shifts become the same).

To avoid mode coupling I had to reduce the octupoles current. I chose then to scan a stability diagram at -10A. There was a trade-off between high octupoles current to have bigger tune-shifts, so faster instability (for the simulation time); and low octupoles current to have small tune-shifts and be far away from mode-coupling.

This time I checked the threshold of Mode coupling and verified that it was at least five times higher than the beam intensity (0.2 mA).

Figure 20: Scan of the stability diagram at -10A

With the HEADTAIL simulations I obtained less than a factor 2 difference between HEADTAIL and Sacherer. This time I tried to change the number of turns over which I do the FFT and over which I fit the average position, so that I can estimate a range of the tune-shift that takes into account at least a part of the post-processing errors; but also can introduce errors if there are some damping during the instability. For example, in the fourth plot of the *Figure 21* the imaginary part has a huge error bar. The fit should be the envelope of both of the rising parts, when the number of turns is reduced the fit is not very good, but if one considers all the simulation turns, there is less than a factor 2 error (I took in account this effect because maybe someone else will do the same simulation but with different number of turns). The results of the points are given in *Figure 21*. Then I launched an octupoles current scan with

HEADTAIL. As one can see on *Figure 22* to *Figure 33*, all the points stabilize between -4A and -6A. Which brings the factor 2 for the second time.

Figure 21: Results for the scanned curve at -10A (Sacherer tuner-shift in dark blue, a range of the HEADTAIL tune-shift in light blue)

Figure 24: Average horizontal position for different octupoles currents OA (red), -2A (green) and -4A (blue).

: Average horizontal position for different octupoles currents -4A (red), -6A (green) and -8A (blue)

Figure 26:Average horizontal position for different octupoles currents0A (red), -2A (green) and -4A (blue).

Figure 27: Average horizontal position for different octupoles currents -4A (red), -6A (green) and -20A (blue)

Figure 28: Average horizontal position for different octupoles currents OA (red), -2A (green) and -4A (blue).

Figure 30:Average horizontal position for different octupoles currentsFigure 31:OA (red), -2A (green) and -4A (blue).

Average horizontal position for different octupoles currents -4A (red), -6A (green) and -10A (blue)

Figure 32: Average horizontal position for different octupoles currents F OA (red), -2A (green) and -4A (blue).

Figure 33: Average horizontal position for different octupoles currents -4A (red), -6A (green) and -10A (blue)

This factor 2 is still unexplained but there are three possible reasons:

- An error in the implementation of the stability diagram
- An error in the computation of the action variables coefficients in HEADTAIL.
- The theory is not precise

These three ideas are being investigated at the moment.

The same method is now applied to scan the positive curve and to see whether it is the same factor (almost 2) in both cases or not. For the moment, I already have the points on the curve (*Figure 34*), I checked their mode coupling threshold and launched their HEADTAIL simulations with and without octupoles.

Figure 34: Scan of the stability diagram at +10A

For the last two scans (-10A and +10A), I changed the output of HEADTAIL to get rid of all the outputs I don't need which extremely reduced the size of the outputs and allowed me to make more simultaneous simulations. That's the main reason why the current scan step in HEADTAIL is currently only 2A.

VI. Conclusion

The goal of this project was mainly to benchmark theory against simulations. The theory here was Sacherer's formula and the stability diagram while the simulation code used was HEAD-TAIL_impedance. This benchmarking was never done before and it was really interesting to check that what is important is the stability curve, as two beams with totally different complex tune-shifts need the same current to be stabilized. It is also amazing to see how a simple formula like the Sacherer one is very powerful and can give a result within a factor 2 in 10 minutes (compared to a simulation that takes weeks). After facing a lot of problems in implementation, theory, simulation, storage capacity, etc. I finally managed to get a scan of the curve that works and that gives a tune-shift and a stabilizing current which are within a factor 2 compared to theory. These results show also how the HEADTAIL code is a reliable and a powerful code.

This project began on the 2nd of May and will continue until the 17th of September. That's why there is still some work to be completed like the positive curve and I probably will try to change the distribution function in HEADTAIL and try to see its effect on the stability diagram as predicted in Ref. [8,9].

This internship was a great opportunity for me to discover instabilities and collective effects. Even if my work was focused on a particular study case, I attended many meetings and talks where I learned many things especially that it is very easy to learn new things when one doesn't know the field at all.

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Appendix: Example of a LHC HEADTAIL input file

Flag for bunch particles (1->protons 2->positrons 3&	4->ions): I				
Number of particles per bunch:	Í 15e+9				
Horizontal beta function at the kick sections [m]:	65.9756				
Vertical beta function at the kick sections [m]:	71.5255				
Bunch length (rms value) [m]: 0.056					
Normalized horizontal emittance (rms value) [um]:	3.75				
Normalized vertical emittance (rms value) [um]:	3.75				
Longitudinal momentum spread: 0.00012					
Synchrotron tune:	0.0028911				
Momentum_compaction_factor:	0.0003225				
Ring circumference length [m]:	26658.883				
Relativistic gamma:	3730.26				
Number of kick sections:	I				
Number of turns:	200000				
Multiplication factor for pipe axes	10				
Multiplication factor for pipe axes	10				
Longitud extension of the bunch (+/-N*sigma z)	2.				
Horizontal tune:	64.31				
Vertical tune:	59.32				
Horizontal chromaticity:	6				
Vertical chromaticity:	0				
Flag for synchrotron motion:	I				
Number of macroparticles: 1000000					
Number of bunches:					
Number of slices in each bunch: 50	0				
Spacing between consecutive bunches centroids [m]:	7.5				
Switch for bunch table:	0				
Switch for wake fields:	I				
Switch for pipe geometry (0->round 1->flat):	9				
Number of turns for the wake:	10				
Res frequency of broad band resonator [GHz]:	1.0				
Transverse quality factor:	Ι.				
Transverse shunt impedance [MOhm/m]:	0.				
Res frequency of longitudinal resonator [MHz]:	200				
Longitudinal_quality_factor:	140.				
Longitudinal_shunt_impedance_[MOhm]:	0.0				
Conductivity_of_the_resistive_wall_[1/Ohm/m]:	l.e6				
Length_of_the_resistive_wall_[m]:	69110.				
Switch_for_beta:	0				
Switch_for_wake_table:	6				
Flag_for_the_tune_spread_(0->no_I->space_charge_2->random): 0					
Flag_for_the_sc-rotation(0->local_centroid_1->bunch_centroid): 0					

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Flag_for_the_space_charge:	0	
Smoothing_order_for_longitudinal_space_charge:	3	
Switch_for_initial_kick:	I	
x-kick_amplitude_at_t=0_[sigmas]:	0	
y-kick_amplitude_at_t=0_[sigmas]:	0	
z-kick_amplitude_at_t=0_[m]:	0.	
Switch_for_amplitude_detuning:	0	
Linear_coupling_switch(1->on_0->off):		0
Linear_coupling_coefficient_[1/m]:		0.0015
Average_dispersion_function_in_the_ring_[m]:		0.0
Sextupolar_kick_switch(1->on_0->off):		0
Sextupole_strength_[1/m^2]:	0.254564	
Dispersion_at_the_sextupoles_[m]:		2.24
Switch_for_losses_(0->no_losses_1->losses):		I
Second_order_horizontal_chromaticity_(Qx"):		0.
Second_order_vertical_chromaticity_(Qy"):		0.
Number_of_turns_between_two_bunch_shape_acquisiti	ons:	I
Start_turn_for_bunch_shape_acquisitions:		190000
Last_turn_for_bunch_shape_acquisitions:		190020
Main_rf_voltage_[V]:	1600000)
Main_rf_harmonic_number:	35640	
Initial_2nd_rf_voltage_[V]:	0.	
Final_2nd_rf_cavity_voltage_[V]:	0.	
Harmonic_number_of_2nd_rf:		18480
Relative_phase_between_cavities:	0.	
Start_turn_for_2nd_rf_ramp:	2000	
End_turn_for_2nd_rf_ramp:	3000	
Linear_Rate_of_Change_of_Momentum_[GeV/c/sec]:		0.
Second_Order_Momentum_Compaction_Factor:		0.
Max_phase_shift_delay_after_transition_crossing_turns]:	I
LHC_octupole_current:		0

Summary

This internship was performed at European Organization for Nuclear Research (CERN) from the 2nd of May to the 17th of September. It was about the collective effects and more precisely impedances. The main goal of this project was to benchmark theory against a simulation code called HEADTAIL; and try to reproduce the so called stability diagram.

First of all, I started with a simulation of the LHC but only with its dipolar component. The results were satisfying; less than a factor 2 difference between theory and simulation. Then, I scanned a curve of the stability diagram using Sacherer's formula for different resonator impedances. I also found satisfying results for an octupoles current of -10A. Since I still have 3 more weeks to continue the project, I already launched other simulations for an octupoles current of +10A and I am also planing to change the transverse distribution of the beam in HEADTAIL to see its effect on the stabilizing current.

This internship was a great opportunity to discover the world of collective effects and impedances. It is one of the main motivations I had when I decided to continue working and doing my PhD in this field.

Résumé

Ce projet de fin d'études s'est déroulé à l'Organisation Européenne pour la Recherche Nucléaire (CERN); du 2 mai 2011 jusqu'au 17 septembre 2011. Le travail effectué était surtout dans le domaine des effets collectifs et plus précisément les impédances des accélérateurs de particules. Le but principal du projet était de comparer la théorie et un code de simulation appelé HEADTAIL, en essayant de retracer un diagramme de stabilité grâce à HEADTAIL.

Tout d'abord, j'ai commencé par une simulation du LHC avec uniquement la composante dipolaire de son impédance. Les résultats de cette simulation étaient satisfaisants avec moins d'un facteur 2 de différence. Ensuite j'ai balayé la courbe de stabilité en utilisant la formule de Sacherer pour différentes impédances de résonateur et avec -10A pour le courant des octupoles. Les résultats de ces simulations étaient aussi en accord avec la théorie. Actuellement, j'attends les résultats des simulations que j'ai faites pour la courbe avec un courant dans les octupoles de +10A. Pendant les trois semaines qui me restent, je prévois de changer la distribution transverse dans le code HEADTAIL pour voir son effet sur le diagramme de stabilité.

Ce projet m'a permis de découvrir le domaine des effets collectifs; et a été une des principales raisons de ma décision de faire ma thèse et de continuer de travailler dans le domaine des effets collectifs.